



# Introduction to Digital Signal Processing

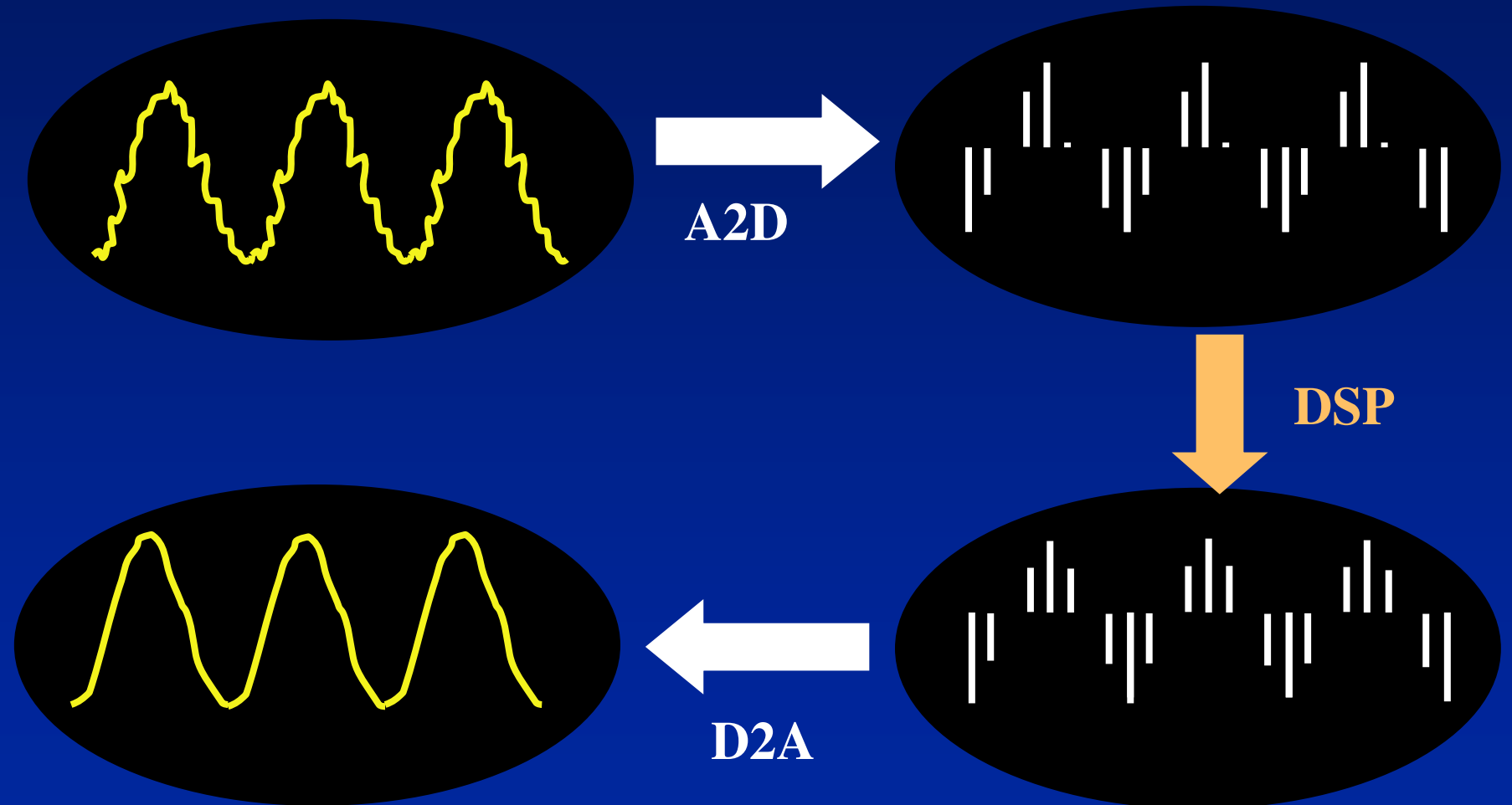
# Digital Signal Processing

- ◆ Perform useful transformations on signals represented in discrete form
- ◆ Challenges
  - Process information **fast**
    - Often deal with real world signals
  - Process **enough** information
    - Ensure no useful information is lost

# Why is DSP so popular

- ◆ Repeatability
  - component tolerances very high
- ◆ Versatility
  - can be reprogrammed
- ◆ Simplicity
  - many transformations done easily in digital domain

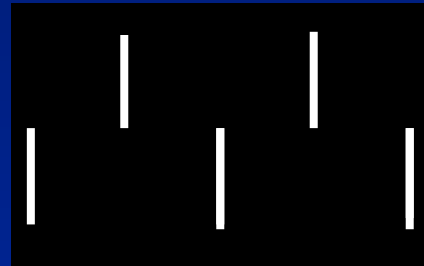
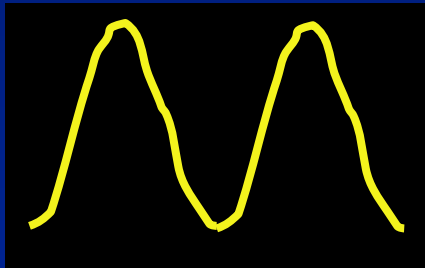
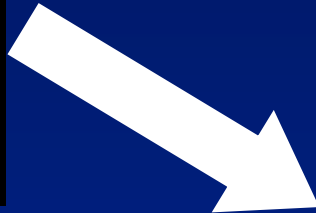
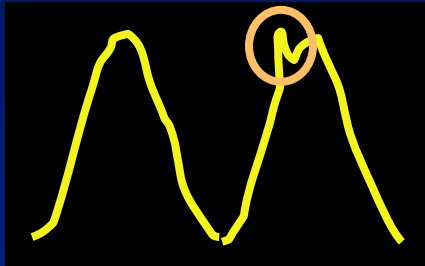
# Typical DSP flow



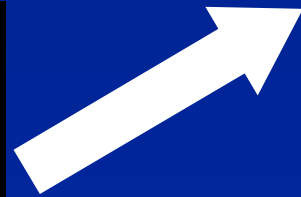
# Digitization Issues

- ◆ Sampling clock errors
  - bad for timing
- ◆ Sample measurement accuracy
  - bad for small changes
- ◆ Finite length of sampling
  - bad for slow changes
- ◆ Finite sample intervals
  - bad for fast changes

# Effect of low sampling-rate

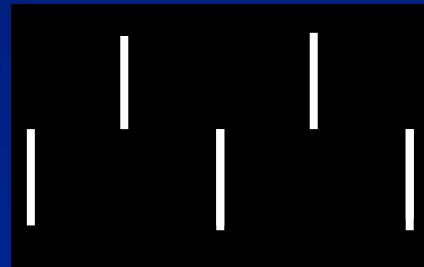
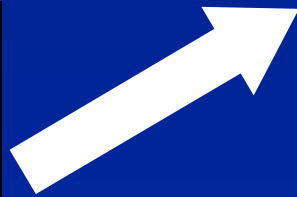
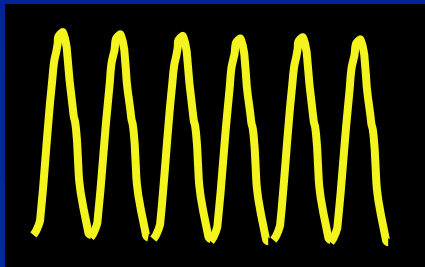
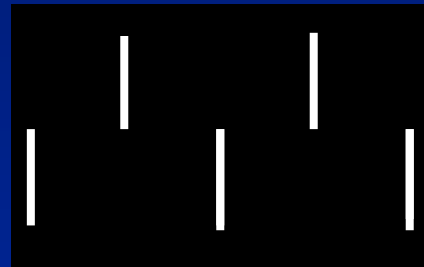
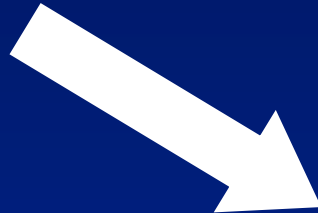
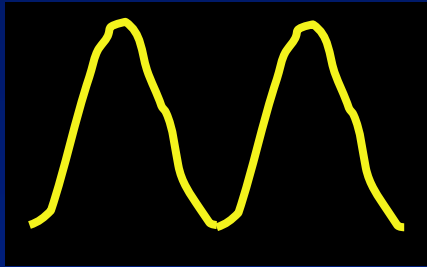


- ◆ Miss glitches



- ◆ Miss high frequency components

# Aliasing



- ◆ Interpret a high frequency as a lower one wrongly

# Aliasing

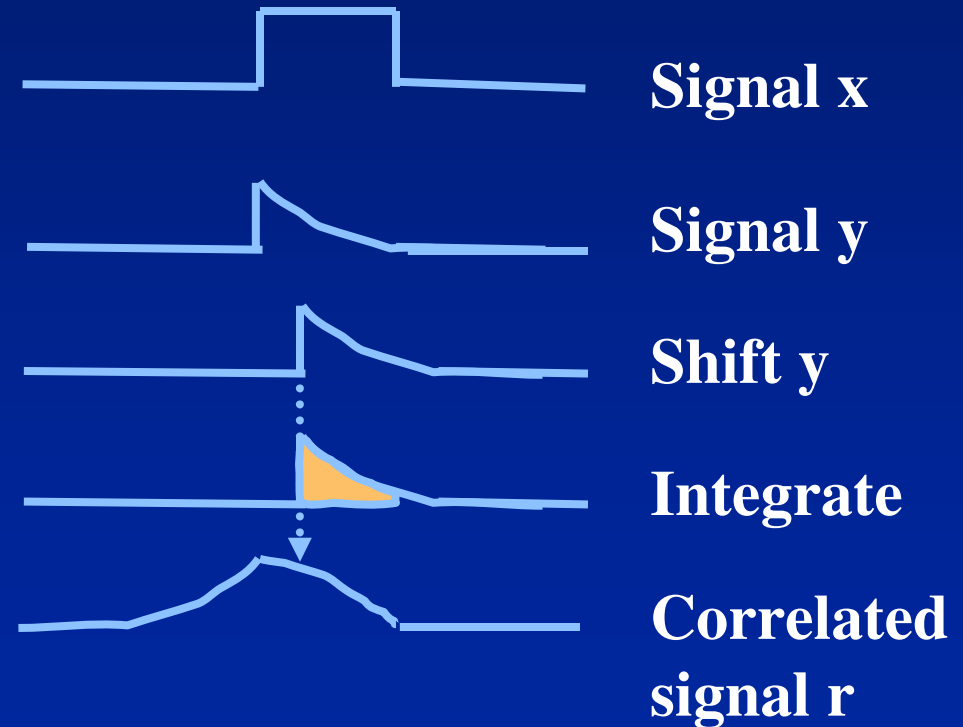
- ◆ Nyquist: :  $\text{sampling-rate} \geq 2 * \text{largest\_sig\_freq}$
- ◆ Avoiding aliasing
  - use antialiasing filter before sampling
  - inhibits freq components  $> 0.5 * \text{sampling\_rate}$



# Time domain processing

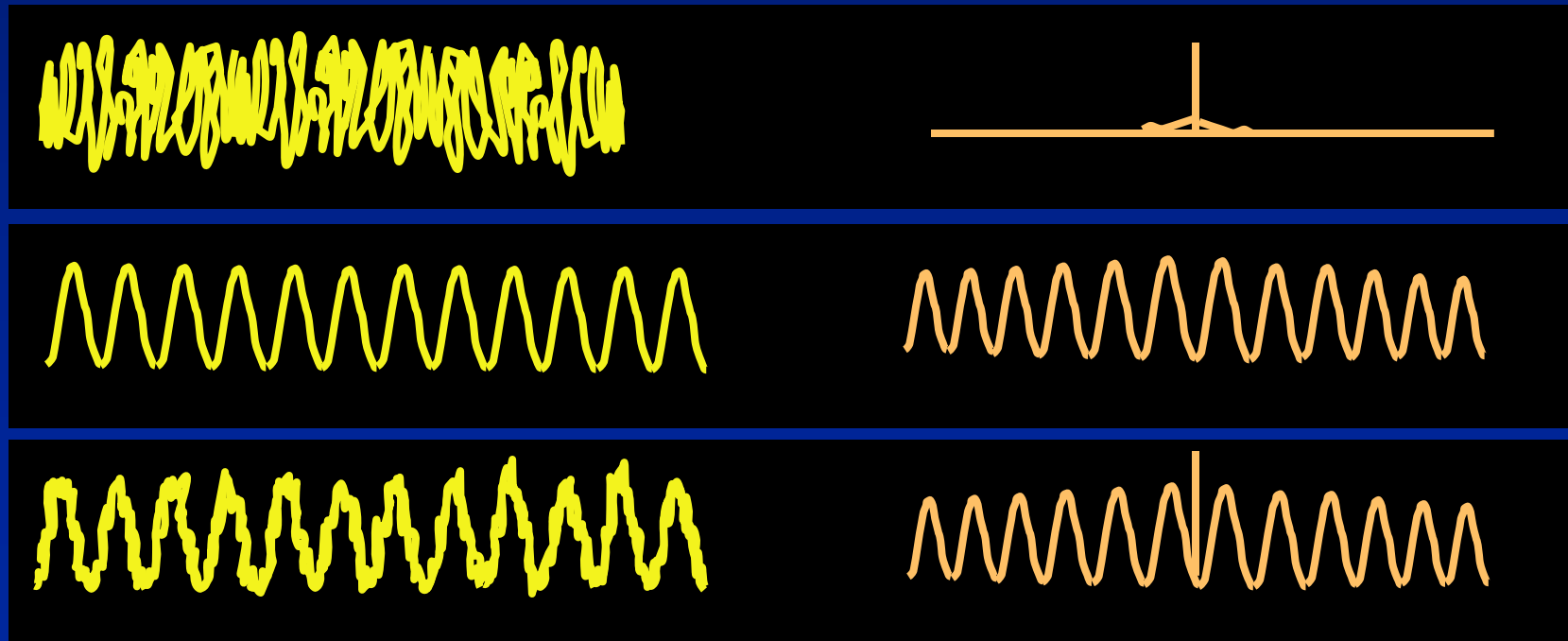
## ◆ Correlation

$$r(n) = \sum_{k=0}^{N-1} x(k) \times y(n+k)$$



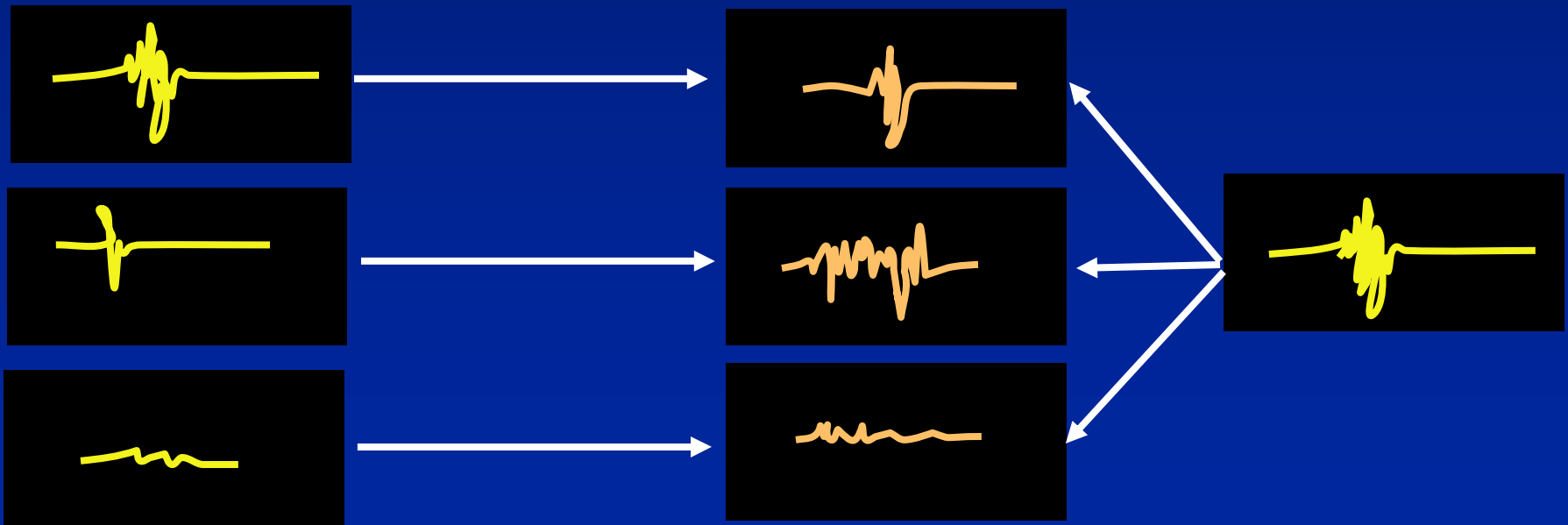
# Correlation

- ◆ Autocorrelation
  - extract signal from noisy environment



# Correlation

- ◆ Cross correlation
  - correlate input signal with library of signals



# Convolution

$$X(\omega) = \sum_{k=0}^{N-1} x(k) \times e^{-\frac{j2\pi\omega k}{N}} \quad Y(\omega) = \sum_{p=0}^{N-1} y(p) \times e^{-\frac{j2\pi\omega p}{N}}$$

$$R(\omega) = X(\omega) \times Y(\omega) = \sum_{k=0}^{N-1} x(k) \times e^{-\frac{j2\pi\omega k}{N}} \times \sum_{p=0}^{N-1} y(p) \times e^{-\frac{j2\pi\omega p}{N}}$$

$$= \sum_{n=0}^{N-1} \sum_{k=0}^{N-1} x(k) y(n-k) \times e^{-\frac{j2\pi\omega n}{N}}$$

$$R(\omega) = \sum_{n=0}^{N-1} r(n) \times e^{-\frac{j2\pi\omega n}{N}}$$

# Convolution

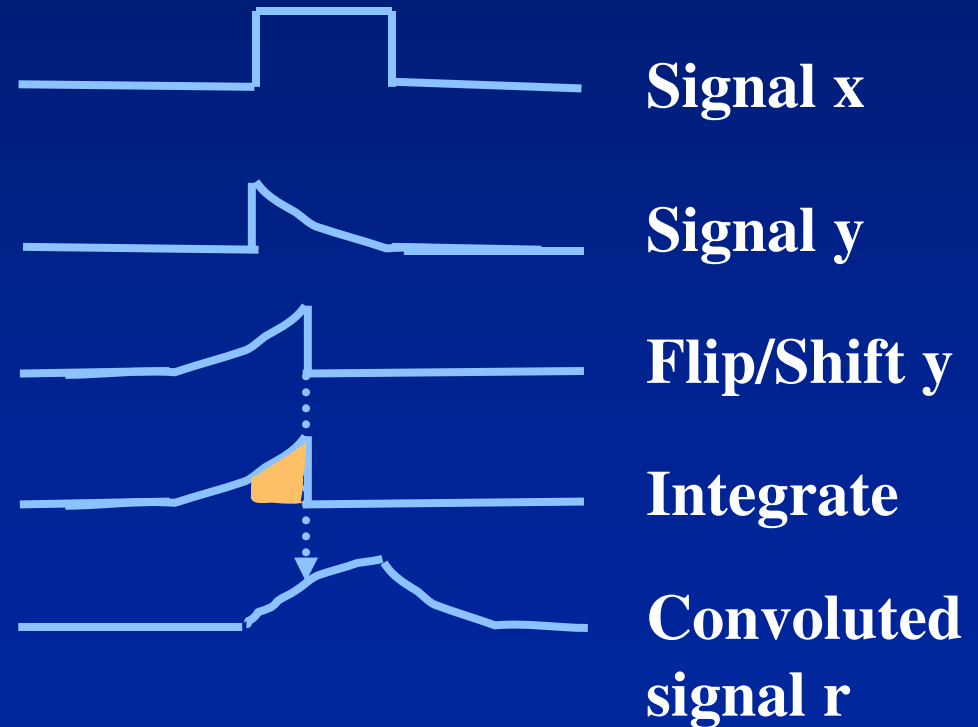
$$R(\omega) = X(\omega) \times Y(\omega) \Rightarrow$$

$$r(n) = \sum_{k=0}^{N-1} x(k)y(n-k)$$

- ◆ Multiplication in frequency domain  $\Rightarrow$  convolution in time-domain

# Convolution

$$r(n) = \sum_{k=0}^{N-1} x(k) \times y(n-k)$$



# Time domain processing

- ◆ Correlation

$$r(n) = \sum_{k=0}^{N-1} x(k) \times y(n+k)$$

- ◆ Convolution

$$r(n) = \sum_{k=0}^{N-1} x(k) \times y(n-k)$$

- ◆ Multiply/accumulate are the most widely used core functions for DSP

# Conclusions

- ◆ Why DSP is popular
- ◆ Effect of sampling
- ◆ Aliasing
- ◆ Correlation
- ◆ Convolution



# VLSI Signal Processing in FPGAs

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# Sections

- ◆ Introduction to DSP
- ◆ VIRTEX Architecture
- ◆ Filters in FPGAs
- ◆ FFTs in FPGAs
- ◆ MPEG decoding in FPGAs
- ◆ Cordic Algorithms in FPGAs
- ◆ Low-power solutions
- ◆ Specific DSP architectures as FPGAs